

How an information perspective helps overcome the challenge of biology to physics.

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Abstract

Living systems have long been a puzzle to physics, leading some to claim that new laws of physics are needed to explain them. Separating physical reality into the general (laws) and the particular (location of particles in space and time), it is possible to see that the combination of these amounts to efficient causation, whereby forces are constrained by patterns that constitute embodied information which acts as formal cause. Embodied information can only be produced by correlation with existing patterns, but sets of patterns can be arranged to form reflexive relations in which constraints on force are themselves formed by the pattern that results from action of those same constrained forces. This inevitably produces a higher level of pattern which reflexively reinforces itself. From this, multi-level hierarchies and downward causation by information are seen to be patterns of patterns that constrain forces. Such patterns, when causally cyclical, are closed to efficient causation. But to be autonomous, a system must also have its formative information accumulated by repeated cycles of selection until sufficient is obtained to represent the information content of the whole (which is the essential purpose of information oligomers such as DNA). Living systems are the result of that process and therefore cannot exist unless they are both closed to efficient causation and capable of embodying an independent supply of information sufficient to constitute their causal structure. Understanding this is not beyond the scope of standard physics, but it does recognise the far greater importance of information accumulation in living than in non-living systems and, as a corollary, emphasises the dependence of biological systems on the whole history of life, leading up to the present state of any and all organisms.

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1 Introduction

Since Schrödinger (1944) famously mused that “other laws” of physics might be necessary to explain life, several authors have suggested that biology demands new physics to explain how the animate arises from the inanimate (e.g. Rosen, 1991; Walker, 2017). Many still agree with Mayr (1997, p.32) that biology and physics are separate and “autonomous” sciences, perhaps implying that biology cannot be wholly derived from physics, but more likely because they see no need for deriving life from physical laws. Kauffman (2020) concludes that life is beyond the explanatory power of the laws of physics because of its historical contingency. This arises from the particular (the locations in space and time of every particle), but for inanimate physical systems, such contingency is mostly just random noise that can be removed by course graining to leave relatively simple initial and boundary conditions (weather modelling presents a challenge, but is still partially susceptible). Such coarse-graining is inappropriate only when the particular remains important to the trajectory of the whole system for an extended time. When variations are not diffused away by thermal noise, but are reinforced and accumulated into a formative memory (by positive feedback), then the pattern of particles at time t has considerable effect on the pattern at later time $t + T$, which is the problem we have in understanding life (and to a lesser extent, the weather). Here it is argued that understanding the way ‘the particular’ (which will be identified with information) constrains ‘the general’ (especially physical forces), plus the way biological systems preserve information by embodying it in systems that are closed to efficient causation, including the translation from arbitrary ‘code’ to physical force fields, could bridge the gap between physics and biology.

All patterns of matter and energy in space and time are axiomatically equivalent to *embodied information*. The word ‘information’ alone is better reserved for *relational information*, which is information presented by system A about system B , rather than just that embodied in A . Embodied information is that which specifies the form of the object which embodies it, simply by virtue of the embodiment: it equates to the information that would be necessary and sufficient to recreate the pattern that is the *form* of the object (see Floridi (2003, 2005) for detailed explanation). For example a DNA sequence has a form that can be written as a nucleotide string (A.G.T.C...), this pattern being embodied information, which only in the context of ‘reading’ (more generally interaction with another pattern), becomes relational information, i.e., information as we usually understand it (the *Shannon* sense). An *informed system* is one which uses additional information beyond that embodied in its own form; e.g., the genome of an organism, or the operating system of a computer are additional to the metabolic components and the hardware respectively. Closure to efficient causation (hereafter *clef*) describes a closed loop in causal relations, where e.g. A is the efficient cause of B and B is the efficient cause of A (developed in detail by Louie (2009), Sect 6.16). Efficient cause will be defined in section 2.4.

The aim of this work is to root within physics the main organisational systems-biology concepts that have proved useful to understanding life as a process (e.g., in Hofmeyr

68 (2021)). The method will be to build up an explanation of them using information-
69 based concepts, from the origin of information, through its role in causation and the
70 way different kinds of causation are combined into multi-level causal structures, cyclic
71 organisational systems and the information processing from which autonomy arises.

72 **2 From fundamental physics to a practical model** 73 **of causation**

74 In this first section, a concept of formal, efficient and material cause is built to become
75 the foundation for considering living systems as causal systems.

76 **2.1 The physical roots**

77 The overarching axiom of this work is that physical reality is the consequence of dy-
78 namic patterns of matter and energy in space and time. Philosophically, this places
79 it roughly in the Information Structural Realist camp (attributed to Floridi (2008)),
80 but perhaps with a more committed view on structure than objects (Floridi aimed for
81 minimal commitment to both). Specifically, the present work does not concern human
82 thoughts, minds or any putative reality beyond the natural world with which physics
83 and other sciences deal – see Gillies (2010). The commitment to structure over material
84 comes from the fact that patterns are the source of variety and dynamic behaviours in
85 the natural world, with matter and energy performing the role of a substrate through
86 which patterns act in space and time. The substrate is necessary for the natural world as
87 is the space and time in which it can be arranged. But without particular arrangement,
88 natural reality would be no more than uniformly random—the expected eventual ‘heat
89 death’ outcome for the universe. It is therefore pattern, i.e., non-uniformity of arrange-
90 ment, that brings about anything interesting in the universe and the pattern is what
91 we interpret as embodied information. We may remind ourselves that the behaviour of
92 molecules can be completely described by Schrödinger’s equation, written here in time-
93 independent, but explicit space with n electrons and nuclei having space coordinates
94 $\underline{\mathbf{x}} = \mathbf{x}_1, \mathbf{x}_2, \dots \mathbf{x}_n$:

$$\hat{\mathbf{H}} \Psi(\underline{\mathbf{x}}) = E \Psi(\underline{\mathbf{x}}) \text{ where,} \tag{1}$$

$$\hat{\mathbf{H}} = \sum_{i=1}^n \frac{-\hbar}{2m_i} \nabla_i^2 + \sum_{i=1}^n \sum_{j=i+1}^n \frac{q_i q_j}{4\pi\epsilon_0 |\mathbf{x}_i - \mathbf{x}_j|}$$

95 is the Hamiltonian consisting of the classic kinetic energy (first term with masses m_i)
96 and electrostatic energy (second term, with charges q_i, q_j). This emphasises that the
97 behaviour of the system: a) obeys general constraints of fermion exchange and anti-
98 symmetry ($P\psi = (-)^P\psi$) and b) depends on the *particular* arrangement of particles
99 in space, i.e. particular constraints on the system. This general/particular dichotomy
100 is consistent with the philosophical insight of Howard Pattee (1982; 1995; 2001), who

101 identified an epistemic separation between physical and semantic (symbolic) representa-
 102 tions of reality, the two being complementary and both necessary for life. The physical
 103 consists of particles, waves and forces; the semantic consists of patterns among these in
 104 space and time. Physical laws are definitively universal, whilst patterns are definitively
 105 particular and both together inform the structure and behaviour of matter-energy in
 106 space-time. Without referring to semantics (and its connotations of cognition), we can
 107 simply say that reality results from the particular constraints imposed by patterns on
 108 the shape of force fields that obey the general laws of physics.

109 2.2 The origin of pattern information

110 Heat ensures that particles of matter are in constant motion. In constantly chang-
 111 ing configurations of ensembles, patterns will occasionally appear spontaneously—they
 112 will have no significance at all and will disappear as fast as they arrived. Any one of
 113 these transitory patterns is no different from any other configuration in random vari-
 114 ation. Conversely, information is definitively non-random. In the absence of anything
 115 else, only the improbable persistence of a pattern can lead us to suspect the presence
 116 of information. That is, no particular momentary pattern is special—even if particles
 117 fleetingly configure to form a recognisable object. If, however, they form a configuration
 118 that—without intervention—persists, then something must be biasing the probability of
 119 configurations. More precisely, in a system of n particles having time-dependent state
 120 coordinates for position and velocity $\mathbf{z} = x_i(t), v_i(t)$, ($i = 1\dots 3$), information is embod-
 121 ied within the system if for at least two particles their time-series $\mathbf{z}(t)$ are correlated.
 122 Equivalently, if $d_m(t) = \sum_{m-1}(d_{j,i})$ is the sum of spatial distances ($\mathbf{x}_j - \mathbf{x}_i$) among a set
 123 of $m < n$ particles, then there is information if $\frac{d}{dt}d_m(t) < \bar{D}_n$, where \bar{D}_n is the constant
 124 (mean) displacement rate (diffusion rate) of particles in the system of n , i.e., integrat-
 125 ing $d_m(t)$ w.r.t. t , the total mutual displacement among the m particles after time T :
 126 $d_m(T) < \bar{D}_n T$. Information—as pattern in a natural dynamic system—can therefore
 127 be identified with the ‘stillness’ of the pattern relative to that expected from random
 128 displacement. Note this implies that a ‘frozen’ pattern (temperature = 0°K), embodies
 129 information: it holds information at time t about its its configuration at time $t - T$
 130 (though no information about when it froze). This information transmission through
 131 time is fundamental to defining an object since the object only exists because it is a
 132 persistent pattern and that is only because information about its configuration at the
 133 time of observation (t) informs the observer of its configuration at an earlier time ($t - T$).
 134 Embodied information of this kind serves to give existence (diachronic identity) to an
 135 object for which all the material parts are continually replaced, e.g., a vortex in a fluid.

136 Patterns can only be persistent if they are reinforced: physical forces must influence
 137 the trajectories of the moving particles so that the inequality $d_m(T) < \bar{D}_n T$ remains
 138 true. Physical forces emanate from the particles themselves (in general only from par-
 139 ticles). The direction and strength of these forces at the locations of the particles is
 140 determined by the positions of the particles relative to one another. Reinforcement thus
 141 results from the pattern in the vector sum of forcefields being positively correlated with

142 that of the pattern in particle locations.

143 One obvious cause of persistent pattern, and probably the first acting in the history
144 of the universe, is gravity. It is self-reinforcing because it concentrates matter in space,
145 creating a pattern that further concentrates the gravitational forces. All force fields are
146 limited in extent only by the light-cone of special relativity, though their effective range
147 is inversely related to the mass of their exchange boson, which is believed to be zero for
148 gravitons and must be zero for photons. What the placement of force-generating bodies
149 does is determine a particular shape of the forcefield (over all space) for a particular
150 configuration, thereby specifying the coordinates of the force-generating particles, in
151 space and time, effectively constraining the forcefield. Any pattern of particle locations
152 is, in turn, influenced by the forces that it constrains. The emergent feedback between
153 displacement and force leads to an attractor (e.g., a black hole, or the equilibrium of a
154 mass-spring system).

155 Since all forces can be represented by vectors, the constraint is the determination
156 of a particular direction for the force acting between bodies set at particular locations
157 in space and time. Imposing the particular over the general is both a potential source
158 of information (by creating a pattern) and also a consequence of pattern (information)
159 constraining the system. Some have wondered how ‘intangible information’ can influence
160 physical reality, but if ‘patterns of force fields affecting particles’ is all we observe and
161 if ‘pattern in matter and energy distribution is embodied information’, then it is not a
162 mystery. Persistence of a pattern, as opposed to a transient state in random reconfigu-
163 ration, is achieved only when the pattern exerts a positive feedback to make itself more
164 likely than any other possible configuration.

165 The persistent configuration that results from reinforcement is the foundation for
166 information, but not sufficient to call it information in a useful sense. A pattern which
167 just persists in isolation is static (frozen) and the most we can say about its causal
168 power is that it causes its own persistence. More interesting, by far, is the effect of one
169 pattern on another, either interacting with it, or creating it *de novo*. The only way one
170 pattern can create another is by ‘selecting’ it from among random configurations through
171 correlation. This is the way crystal structures grow. Once a self-reinforcing pattern is
172 established in the electrostatic force field around atoms, randomly appearing patterns
173 in the local milieu of free atoms, which just happen to match the crystal structure
174 sufficiently well (i.e., spatially correlate with it) are selected by mutual attraction to
175 become part of it. The selection referred to here is the filtering of configurations, from
176 all randomly occurring configurations, only those that match the existing pattern and
177 this is physically achieved by constraining force field shapes: their particularisation.

178 **2.3 Relational information**

179 When more than one pattern forms it is possible for members of the set of patterns
180 to interact. The physical effect of a pattern in a force field is to constrain the form of
181 any force-carrying configuration that it encounters. The constraint by a single pattern
182 is, by geometric necessity, that of exerting a pattern which reflects its own: selection
183 by correlation, either of self (reinforcement) or selection of correlated patterns from a

184 random milieu, as in crystal growth. The result is that the force-interacting patterns
 185 will tend to match with one another—a (muted or partial) reflection of each will form in
 186 the other and they will therefore share mutual information. The map of forces observed
 187 by atomic force microscopy (from Albrecht et al. (2015, Fig.3)) illustrates the effect of
 188 this beautifully.

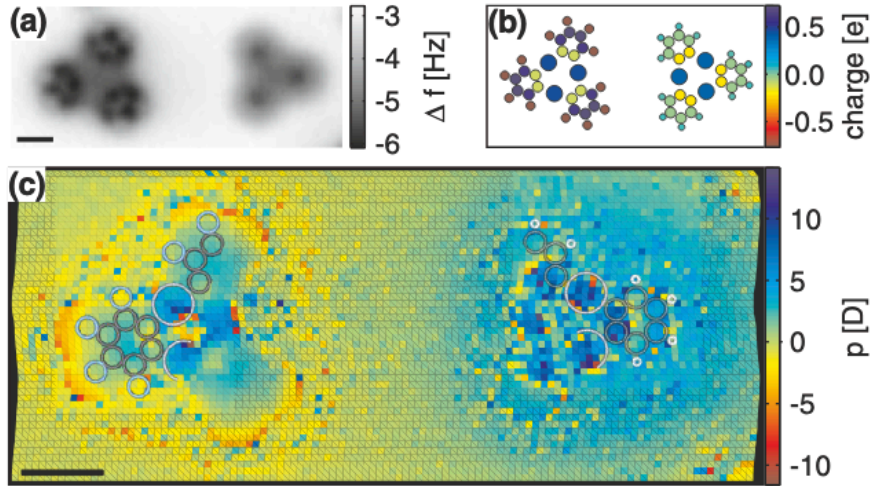


Figure 1: Kelvin probe force microscopy spectral map of electric charge distribution (force field) generated around two molecules which induce a dipole in each other (sharing information). The force distribution and direction is specified by the probability distribution of electrons which is constrained by the particular locations of nuclei, which in turn are constrained by the force mediated interactions among all the electrons and nuclei, reaching a minimum Gibbs free energy configuration. Reproduced from Albrecht et al. (2015, Fig.3), where original caption read: “Highly resolved dipole-distribution map. (a) Δf image recorded at $z = 9.6\text{\AA}$. (b) Calculated charge distribution deduced from Bader analysis. (c) Dipole-distribution map extracted from $\Delta f(Z, V_i)$ spectra for $\text{F}_{12}\text{C}_{18}\text{Hg}_3$ and $\text{H}_{12}\text{C}_{18}\text{Hg}_3$ ($9.6\text{\AA} \leq z \leq 10.1\text{\AA}$; $V_i = -0.2$ and 0.5V)”.

189 Forces induce changes in the patterns that embed shared information, which is then
 190 *relational information* because it now involves ‘information about a thing’, not just

191 information embodied in the pattern of a thing. Relational information is a concept
192 more closely resembling the ‘common sense’ idea of information as a transaction among
193 entities (source and receiver). Force fields have an energy level associated with them
194 because the ensemble that they shape (in space) has potential energy. When one pattern
195 changes or reinforces another, it is usually because the change it induces in the other
196 pattern results in a reduction of the combined Gibbs free energy. Schrödinger conceived
197 of an aperiodic solid that could embody the information needed to inform the structure
198 of an organism, but most chemical systems with that property are inherently displaced
199 from equilibrium and costly (in free energy) to make and maintain. One of the essential
200 and special features (for life) of nucleic acids is that they are very close to thermodynamic
201 indifference regarding which nucleotide is bonded to which, i.e., the Gibbs free energy
202 of any pair is equivalent to any other pair. This feature enables nucleic acids to form
203 patterns of arbitrary length (ℓ), embodying 4^ℓ bits of information in the sequence. (Note
204 - some pairings are slightly more likely than others in undirected sequence formation).
205 The DNA sequence is embodied information about the organism, but unless it is coupled
206 to a system of patterns that can, via forces, assemble into the organism, it has no effect.
207 We next need the information to be causal.

208 2.4 The physical basis of causation

209 Kistler (2021) has laid out the following, very general, criteria for causation:

- 210 1. Events F and G are localized in distant spatio-temporal regions (no spatio-temporal
211 overlap).
- 212 2. The regions in which F and G are localized are time-like (or light-like) related.
- 213 3. The probability of G , given F , is, under certain conditions, higher than the un-
214 conditional probability of G .
- 215 4. G depends, under certain conditions, counterfactually on F .
- 216 5. If F and G are represented by variables f and g , it is possible to intervene on f and
217 interventions on f (obeying the appropriate constraints) are means of modifying
218 g .

219 In common with most modern philosophy of causation, of the four aspects of cause
220 identified by Aristotle (efficient, material, formal and ultimate cause), Kistler (2021)
221 refers primarily to efficient cause, so we will begin with that.

222 The change in the shape of the force field of one pattern resulting from an encounter
223 with another is well illustrated (macroscopically) by a footprint in mud or dent in the
224 side of your car if you hit a lamp post. The permanence of this change—and which pat-
225 tern more substantially changes—is a function of particularities, especially the relative
226 strength of the forces that maintain each pattern and the stability of the patterns under
227 deformation. Colliding billiard balls deform a little on impact and elastically return to
228 their original form, so no information is shared beyond each other’s momentum prior to
229 impact. In the case of a footprint in mud, the mud gains potentially a lot of information

230 from your foot. When two molecules combine into one, they share information about
231 each other's shape and the compound molecule has within it an impression of each sep-
232 arate molecule, not just their original shapes, but each original shape transformed to
233 reflect (partially) the shape of the other.

234 Many philosophers of science believe there is a physical basis to cause and consider
235 the mechanism behind cause as a transfer of a conserved quantity (energy, momentum or
236 something more exotic like charge or spin) in a material system. This is the concept of
237 transference theory attributed to Salmon (1984) and Dowe (2000) which posits that there
238 must be a spatio-temporally continuous connection between one thing X and another
239 Y involving the transfer of energy, momentum (or other conserved quantity) for X to
240 cause Y . The idea that causation, more particularly *efficient causation*, is realised by
241 the transfer of a conserved quantity and that this transference is necessary and sufficient
242 for (efficient) causation, is robustly defended by Kistler (2021). Surprisingly, it has not
243 yet been explicitly mentioned that the transfer of a conserved physical quantity is the
244 current model of physical force and well represented by the Feynman diagram (Fig. 2)
245 in which sub-atomic particles interact via the transfer of an exchange particle, according
246 with the Standard Model of physics (we can include gravity, still rather speculatively).
247 A good example is the fundamental strong nuclear (colour) force between quarks which
248 swap colour on exchange of a colour/anti-colour gluon (Fig. 2, left). In general, forces
249 arise through the exchange of virtual field quanta: gauge bosons. An example more
250 relevant to biology is the electric force of repulsion between electrons (more generally
251 the quantum electrodynamics of scattering among charged particles), generated by the
252 exchange of photons (Fig. 2, right). This is why the physical basis of causation necessarily
253 involves physical force, behind which there is an exchange of gauge bosons to conserve
254 properties in accordance with Noether's theorem, as described by Feynman diagrams.
255 But this is a sort of raw material for causation, not yet formed into functional shape.
256 That is provided by the particular arrangement in time and space of the interacting
257 particles; their positions determining the strength and direction of the interactions, this
258 being particular and thereby embodying information. The result of exchange particles
259 transferring conserved quantities over particular distances in particular directions is the
260 physical basis, indeed the essence, of *efficient cause*.

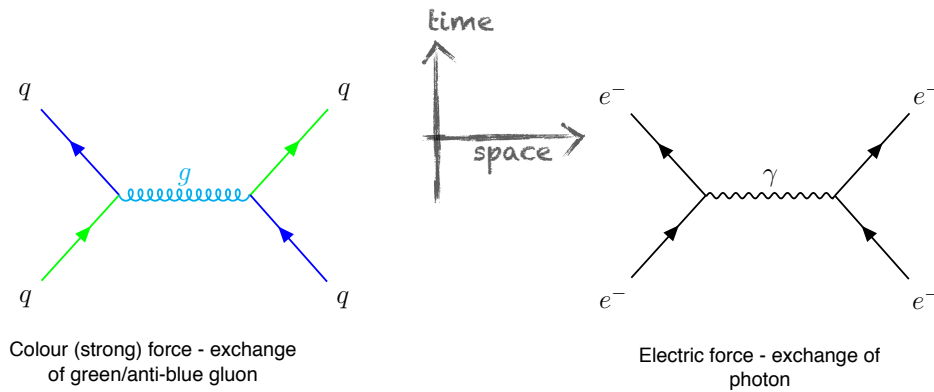


Figure 2: Feynman diagrams representing fundamental forces as the exchange of a gauge boson which conserves properties such as charge and colour. The diagrams respect Noether's theorem (law) and provide a physical explanation for the transference theory of (efficient) causation. The exchange is made obvious in the left diagram representing the strong nuclear force where a blue quark encountering a green quark exchange a green/ anti-blue gluon and thereby swap colours, with the kinematic effect of attraction (not distinguished from repulsion given the generalised space represented in the x-axis). The electrical force between electrons (repelling) comes from the exchange of a photon, which having zero mass, gives an infinite extent to the force field. Note that the process is symmetrical in time (reversible) in both cases (one can reflect the strong force diagram through the vertical and horizontal axes to find an identical diagram).

261 Let us then define efficient causation as **the action of one force pattern on**
 262 **another, either to change it (transferring information among the patterns),**
 263 **or to reinforce it (maintaining stasis).**

264 This definition meets all of the criteria set out by Kistler (2021) above, if we accept
 265 that 'states' (using the language of physics) can be substituted for 'events'. When, for
 266 example monomers come into one another's influence, as patterns in the electrostatic
 267 force field they will affect one another's shape and at some point may find a mutually

268 thermodynamically favourable pattern in which they are bonded (every point in this
269 sequence of ‘events’ can be specified by the states of the particles present in the interac-
270 tion). Significantly, one pattern does not do this to the other; there is no demarcation
271 between causative agent and recipient. The efficient cause of bond forming is the com-
272 bination of the particular pattern of the *total* force field and the general causal power
273 of physical force: pattern informing force to produce efficient cause. This cause is not
274 attributable to any single pattern in the interaction, it is strictly a product of all the
275 patterns interacting simultaneously. A reasonable way to conceive this is not as things
276 with individual identity interacting, but rather as a single extended force field with a
277 particular pattern that dynamically evolves towards minimum Gibbs free energy. With
278 this universal perspective, efficient cause seems compatible with the overall symmetry of
279 physics once again, including the probabilistic arrow of time. That is, causation is seen
280 as no more than a sequence of state changes in the universal field which are *in principle*
281 reversible, though the reverse may be very unlikely in practice as free energy may be
282 needed to enact it.

283 We may ask what efficient cause results from the action of force without constraint
284 by information. Force unconstrained means a forcefield generated by randomly located
285 particles; force vectors among them are random (in direction and magnitude) and the
286 usual source of such random force vectors that may impinge on an established pattern is
287 kinetic energy transfer from randomly moving particles, i.e., heat. The effect of heat on,
288 e.g., proteins or DNA is well known; generally it increases the degrees of freedom of the
289 system being heated and randomises its configuration upon cooling: destroying pattern
290 and with it, destroying information and function. Efficient cause necessarily involves
291 forces together with the particular (information) that constrains their vectors of action.
292 We will now identify that information constraint as the Aristotelean notion of *formal*
293 *cause*.

294 **2.4.1 Formal cause**

295 Formal cause is classically the ‘template’ or design (i.e., information) responsible for a
296 particular outcome of efficient cause. It comes in two distinct kinds. The first may be
297 called the *general conditions*, roughly encompassing ‘the laws of physics’, with at the
298 deepest level, Noether’s theorem (every differentiable symmetry of the action of a phys-
299 ical system has a corresponding conservation law). From this arise the gauge theories
300 and the Standard Model, along with fundamentals such as the ‘principle of least action’.
301 Conservation applies in time to total energy; in space to linear momentum; in rotation
302 to angular momentum and probability is conserved as all possibilities sum to one. The
303 second kind of formal cause may be termed *particular conditions* and concerns the con-
304 sequences of the particular location of particles in space and time and their particular
305 kind (from among all the possible fundamental particles). General formal conditions are
306 strictly single valued (no degrees of freedom) but particular formal conditions are uni-
307 formly probable, subject only to the general conditions (e.g., particles are not allowed to
308 occupy the same space-time coordinates). The appearance of a hierarchy among formal
309 conditions is a consequence of their different degrees of freedom. General conditions

310 constrain particular conditions and both constrain the action of forces to yield efficient
311 cause from the combination of force and formal cause. General conditions are universal
312 both in space and time, so have no memory and are symmetrical in time. This contrasts
313 with particular conditions because at any time t they are necessarily founded on initial
314 conditions at some time t_0 so there is a memory and a direction in time. This depen-
315 dence on initial conditions is one of the great differences between biology (where history
316 is crucial) and physics (where initial conditions perform the auxiliary role of specifying
317 a particular case)—a point recognised by Pattee (1969, 2001).

318 **2.4.2 Material cause**

319 Material cause (that which results from the nature of the substance) can now be seen
320 as a consequence of force field patterns at the atomic scale. It gives water its fluid,
321 solvent, electrostatic and other special properties that are necessary for biochemistry. It
322 also gives steel its strength and hardness (and the temperature dependence of these).
323 Material is governed by formal cause which is the particular spatial arrangement of
324 atoms making particular the pattern of the force field that holds the atoms in place.
325 Traditional material cause, deriving from the composition of substances either acting or
326 being acted upon by efficient cause can be replaced by a ‘micro-formal’ cause, since it is
327 formal cause at the atomic scale. In every case, the interatomic forces are determined
328 by the atomic species (each with its own electrostatic force field) together with their
329 configuration: force constrained by particular form. This effectively unites material and
330 formal cause, both of which generate efficient cause via forcefields.

331 **2.4.3 Biological manifestations of efficient and material cause**

332 Physical forces all either cause acceleration or its prevention and all have an orientation
333 (direction) in space. In the absence of constraints the vector sum of forces acting on
334 each member of an assembly of particles is random and accordingly has no (ensemble)
335 effect, other than pressure (Fig. 3 A).

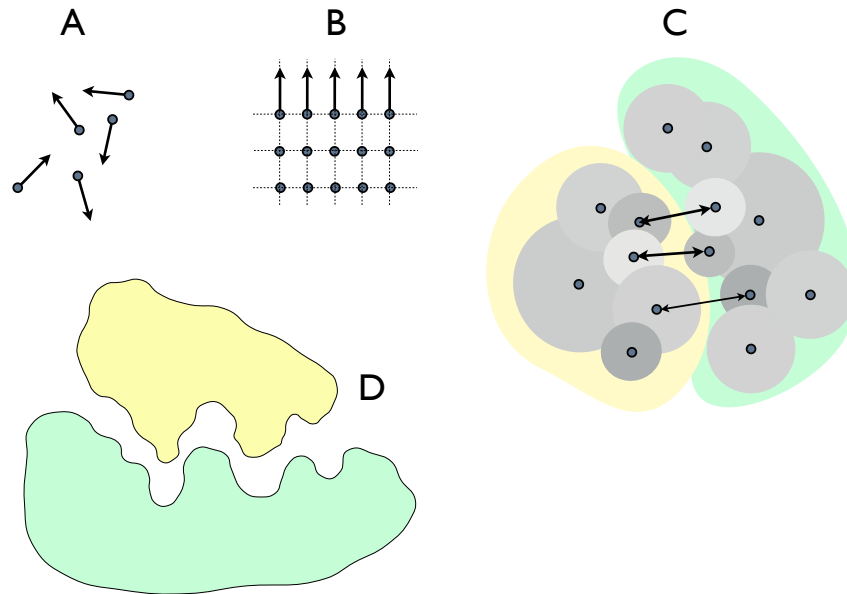


Figure 3: The informational building blocks of biological function. A) random forces are B) constrained by form (in this case a crystalline lattice), resulting in coherent directed forces. C) More information rich forms, as in these bio-molecules, where correlation of patterns in local force fields lead to binding (compare to Fig. 1). D) Correlating patterns of an enzyme and its substrate are the basis of induced fit or lock and key mechanisms with function such as molecular fabrication and cell-signalling, including conformational change. In cases B-D, we may think of the electric forcefield pattern as a whole, with individual molecules as concentrations of force that correlate and share shape information about one another, both reflecting this in their bound shapes. (Adapted and updated from Farnsworth (2021)).

336 Constraints acting on forces reduce the range of directions in which forces can act
 337 among an assembly of particles. The positioning of the constituent parts of a system is
 338 embodied information which can now be termed *form*. When particles are positioned
 339 in a form that is not random, then the form has a coherent spatial structure, i.e., its
 340 parts share mutual information (Fig. 3 B) and this shared information is the basis for
 341 *effective* information (Szostak, 2003). It is effective because it constrains forces such
 342 that it transfers to them its coherence: the directions of the forces are correlated by the
 343 mutual information of the form. The result is that forces, no longer random and merely
 344 producing pressure, act with coherence so that they are available to perform work and
 345 hence functions. For example, the cylinder and piston of a steam engine is a form which
 346 constrains the kinetic force of steam molecules to act in a coherent direction producing
 347 a functional motion against the piston (work); equivalently, mitochondria make use of a

348 constrained flow of protons between inner and outer membranes to produce functional
349 motion. Coherent action enables work to be done and is equivalent to the process we call
350 Aristotle’s efficient cause: the action that brings about a transformation (or resists it).
351 Hence **efficient cause can be interpreted as the constraint of physical forces**
352 **by form**: force acting under formative constraint gives efficient cause.

353 The basic element of efficient cause for biology is the physical configuration of atoms
354 within biologically relevant molecules which, as forms, both constrain and are con-
355 strained by intermolecular forces to act in coherent ways. The effects of these coherent
356 interactions include binding (Fig. 3 C) and electrostatic repelling such as in hydrophobic
357 interactions along with their consequences such as conformational changes: indeed the
358 whole repertoire of biochemical interactions that together produce, e.g., protein folding.
359 Of particular importance in biology, the mutual recognition (correlation) of molecular
360 shapes provides the basis for supra-molecular ‘codes’ (Barbieri, 2015) and the com-
361 munications systems they enable, involving chemical receptors and their ligands, vividly
362 described as ‘lock and key’ (Fig. 3 D) and the machinery of transcription and translation,
363 well illustrated by the set of t-RNAs with their anticodon at one end and amino-acid
364 docking site at the other. Networks of such reversible and specific molecular interac-
365 tions enable information processing at higher levels of organisation (Section 3.1), but we
366 should not forget that underlying even the most abstract and sophisticated biological
367 information processing (e.g., your understanding of this sentence now) is the information
368 sharing by correlation among molecular forms organised into functional networks.

369 **2.4.4 Relation to interpretations of efficient cause in biology**

370 In the relational biology of Robert Rosen (1991) and its further development by Alois-
371 ius Louie (2009; 2013; 2017) the Aristotelean causes are related to each other through
372 category-theoretical mappings. The efficient cause f and material cause A of effect B are
373 related in the mapping $f : A \rightarrow B$. Rosen used graph-theoretic diagrams of such mappings
374 to construct his so-called replicative metabolism-repair or (M,R) -system representation
375 of the functional organisation of the cell (Fig. 4A).

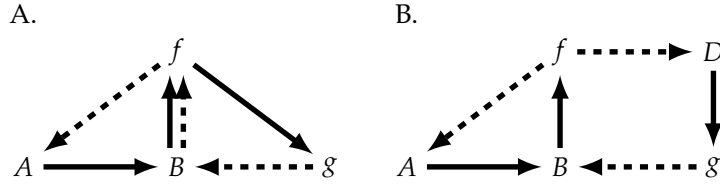


Figure 4: (A) Rosen’s (1991) replicative metabolism-repair or (M,R) -system. Solid arrows represent material causation (e.g. chemical transformations) and dashed arrows show efficient causation (e.g., catalysis). We can interpret material causation as the configuration of matter *plus* the matter itself and efficient causation as the information embodied in form *plus* the electrical (chemical) forces that this information constrains to enact the material transformations. (B) Hofmeyr’s (2021) fabrication-assembly (F,A) -system, an alternative representation of the causal structure of a living cell that realises its biochemical structure (which the (M,R) -system does not).

376 With regard to the incorporation of formal cause into such mappings, Rosen (1989)
 377 suggested

$$f : A \times I \rightarrow B$$

$$(a, i) \mapsto b = f(a, i) \tag{2}$$

378 where $i \in I$ is the formal cause of B . This was also the form underlying the purported
 379 paradox Rosen (1959) claimed to have found in Von Neumann and Burks’s (1966) de-
 380 scription of the universal constructor. However, Hofmeyr (2007) argued that i should be
 381 regarded as acting together with efficient cause f and not with A , and so rewrote this
 382 as (his Eq. 4):

$$(f, i) : A \rightarrow B$$

$$a \mapsto b = (f, i)(a), \tag{3}$$

383 which shows information as the formal cause that, together with efficient cause, forms
 384 the operator of the mapping (note, (f, i) is an element of $\{f\} \times I$, the combination
 385 denoting i *informs* f , where i and f are members of sets I and $\{f\}$ respectively). In
 386 this case, efficient cause is closer to the concept of force constrained by form, so that
 387 (f, i) matches the definition of efficient cause proposed in the present work. Hofmeyr
 388 (2018) developed this further to resolve mappings where formal and efficient cause are
 389 either combined into a single entity (informed efficient cause) by a “choice mapping”
 390 that selects a particular f_i from a set of possible mappings, or act together as separate
 391 entities (f, i) . Incidentally, incorporating information in this way eliminates the “Rosen
 392 paradox” in the universal constructor (Hofmeyr, 2018).

393 Hofmeyr (2021) provides an even clearer account of the different configurations of
 394 formal cause, used for his model of the cell with the causal structure of Fig. 4B, which
 395 is functionally equivalent to the replicative (M,R) -system, but with a structure that
 396 matches the realised biochemical system, thereby solving a longstanding problem in
 397 relating the (M,R) -system to known cellular organisation. He distinguishes three modes

398 of formal cause either acting on (or combining with) efficient cause or acting on material
 399 cause in a material transformation $A \rightarrow B$ (Fig 5). All three can be interpreted in the
 400 present terms: form as pattern, embodying information, combined with physical forces
 401 to give efficient cause.

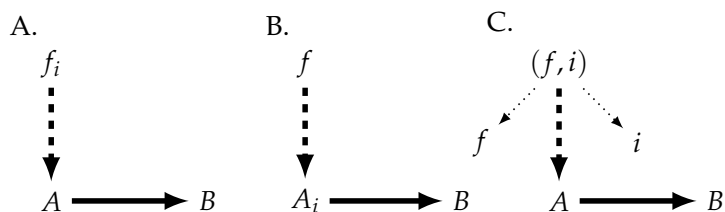


Figure 5: *Formal cause in graph-theoretic diagrams of mappings.* (A) Formal cause i associates with efficient cause f by parameterisation to f_i (a single entity). (B) Formal cause i is intrinsic to material cause A , a propensity of A to transform into B . (C) Formal cause i combines with efficient cause f to form the pair (f, i) , which is an element of the Cartesian product $\{f\} \times i$. The dotted arrows are projection maps that allow f and i to appear as distinct entities in the diagram. Adapted from Hofmeyr (2021).

402 In the first (Fig. 5A), there is a specific formal cause i for B such that the efficient
 403 cause is constrained by the formal cause uniquely identified with B: $f_i : A \rightarrow B$, i.e.
 404 the formal cause is particularised by the form of B , analogous to a particular socket
 405 in a mechanics socket set. The catalytic action of aminoacyl-tRNA synthetase is an
 406 example since each of the set is specific to a particular tRNA amino-acid pairing. This
 407 is a case of a particular form acting via its forcefield in a particular way on some other
 408 form. The formal cause is mediated through correlation among the patterns and the
 409 efficient cause is then the effect of this constraining the combination of forces involved.
 410 Any particular aminoacyl-tRNA synthetase can only match a particular tRNA with a
 411 particular amino acid: all determined by the forms involved constraining forcefields as
 412 shown (in abstract) by Figure 3.D. We can say that f_i is to be found in the form of a
 413 catalyst that is particular to B .

414 In the second mode (Fig. 5B), formal cause is an intrinsic property of the material
 415 cause (note that this is not equivalent to eqn 2, where $i \in I$ is a physical entity separate
 416 from B). This can be explained in terms of an uncatalysed reversible reaction $A \rightleftharpoons B$,
 417 where “the formal cause of B would be the intrinsic propensity of A to transform into
 418 B , while that of A would be the intrinsic propensity of B to transform into A ; in a
 419 sense the formal cause of B can be thought of as a model of B inherent in A , and *vice*
 420 *versa*” (Hofmeyr, 2021). Here the pattern of the molecule A correlates with (carries
 421 information about) that of B such that when thermodynamically conducive ($\Delta G < 0$),
 422 the forward reaction takes place and *vice versa*. For example, the carboxyl group at
 423 one end of an amino acid implicitly embodies information about the amino group at
 424 the other end by correlating with it, and *vice versa*, enabling them to form the peptide
 425 bonds that join them (the mutual information of these patterns is in the shapes of their

426 electrostatic force fields as explained in Section 2.2, analogous to jigsaw pieces that fit
427 together because their shapes correlate). In this mode, formal cause is the constraint of
428 electrostatic forces emanating from each molecule by the forms of the reacting molecules
429 themselves.

430 The third mode (Fig. 5C), is more complicated. Here, the entities to be associated
431 with formal cause i and efficient cause f can be physically separated (Hofmeyr calls them
432 ‘freestanding’). But it is only when they physically associate with each other that they
433 can actually function as formal and efficient causes—their combination is represented
434 by the Cartesian product of the sets to which they belong ($\{f\} \times I$). This is described
435 by saying the efficient cause is informed by the formal cause: the latter is what to
436 do and the former, how it is done. Hofmeyr’s example of this is the combination of an
437 mRNA molecule (freestanding formal cause) with a ribosome (efficient cause) to produce
438 a polypeptide. In this case, the pattern of the mRNA is considered to exert its influence
439 independently of its force field, but more precisely, it is irrespective of the magnitude
440 of the forcefield, so that only the information matters. This is because, to a reasonable
441 approximation, the physical interaction between each nucleotide and the ribosome is
442 constrained to differ in only one way depending only on which of A, G, C or U it is, so
443 the only information exchange is that of the sequence. In information terms, individual
444 nucleotides bring no unique information, only their class information (that of A, G, C and
445 U). In the context of the ribosome (plus aminoacyl-tRNA synthetase and other helping
446 molecules) nucleotides act as quaternary switches making a 3-bit combination lock of the
447 codon to permit the ligation of a single amino acid onto the growing polypeptide chain.
448 The whole translation apparatus constrains the nucleotide forcefields to this unitary
449 effect, in a sense by preempting (or accounting for) any other efficient cause they could
450 enact otherwise. Their very specific embrace within the ribosome neutralises every aspect
451 of their forcefield but one—that which identifies them as A, G, C or U. This is classic
452 machine behaviour in which an apparatus (complex of forms) is arranged to constrain
453 the effect of a class of objects (e.g., the letters of a mechanical type-writer which are
454 constrained by the form of the typewriter to strike a single point and leave an impression
455 of a fixed face). The freestanding efficient cause in this mode is the form-constrained
456 forcefield exerted by the apparatus (ribosome complex) on the interactions between the
457 amino acid and the polypeptide to which it is attached. The classic machine metaphor
458 (and example) is that of a Jacquard loom where the tape serves as formal cause providing
459 additional constraint to a much larger and stronger set of constraints set by the form
460 of the loom, where the puny force difference between tape and its holes is negligible
461 in magnitude, effectively leaving only the information. To say that mRNA is formal
462 cause and ribosome is efficient cause is a reasonable approximation, just as it would be
463 to call the tape of a Jacquard loom ‘pure information’. Rendering the force magnitude
464 negligible with an apparatus, effectively stripping it from efficient cause to leave only
465 information (freestanding formal cause) is of great importance to biological systems as
466 we shall see in Section 3.4. Consistent with the definition of efficient cause given early
467 in this section, it is clear that, even in this mode of causation, to act as an efficient
468 cause, forces cannot stand free from their associated formal cause: without formative

469 constraint we are left with randomness; merely heat.

470 **3 Organising causes with patterns to make wholes with** 471 **agency**

472 Organisms are patterns of patterns interacting through efficient causes that are organised
473 into networks by yet higher level patterns. Here, we build up an idea of how this
474 informational scheme emerges to result in the organism.

475 **3.1 Nested levels of phenomena and emergence**

476 Patterns of patterns, like the mosaic artwork of Anna Halm Schudel, show us how the
477 arrangement of patterns, each having individual properties, can produce apparently
478 novel effects at the larger scale that could never be identified at the smaller scale. This
479 is because the arrangement at the larger scale embodies information that does not belong
480 to the component patterns. This contrasts with a jigsaw puzzle where the shape of all
481 the pieces determines their places in the whole, so all the information effective in the
482 larger pattern is already embodied within its components. In a jigsaw puzzle, the larger
483 pattern is the result of particular formal constraints imposed by the component parts,
484 but in the art mosaic, formal - particular - constraints are additionally embodied at the
485 scale of the larger pattern. Because a large scale pattern can always be broken down into
486 variations at the small scale (e.g., any shape can be digitised or spectrally decomposed
487 with a Fourier transform), the mosaic picture is not, in itself, an example of emergence.
488 Emergence refers to properties and behaviours, not patterns and the main indication
489 for emergence is the appearance of properties and behaviours that could not even be
490 conceived of using lower-level descriptions. For that reason, an emergent-level *effective*
491 *theory* is needed (Ellis, 2020), in which case the properties - and the levels attributed to
492 them - are considered irreducible. One of the recurring themes of biological challenges
493 to physics is the appearance of a hierarchy of irreducible levels (see e.g. Polanyi (1968)),
494 though in physics, such hierarchies have been invoked in accounts of various phenomena
495 (reviewed in Gibb et al. 2019), especially following Anderson's (1972) observations.

496 Taking a biological example, suppose the large scale pattern were a functional molec-
497 ular machine such as the ATP synthase complex (F_0F_1 -ATPase), composed of amino
498 acid sequences (the small-scale patterns). Could we - even in principle - deduce from
499 the amino acids, its ability to add a phosphate to ADP, making ATP? Standing in the
500 way of that are a) the particular sequences of amino acids in the polypeptides, b) the
501 way they are folded into functional proteins, c) the way these are assembled into the ma-
502 chine and d) the way the machine operates dynamically (like a little dynamo). At least
503 folding and the dynamo behaviour are new concepts that are necessarily associated with
504 higher levels of organisation than the amino acids and (because of the thermodynamic
505 equivalence of amino acid sequences) unlike jigsaw pieces, the order in which they are
506 joined is not strictly determined by their individual properties (therefore not predictable
507 from knowledge of them as individuals components). This example, typical of biological

508 systems, shows the appearance of properties that can only be attributed to a larger scale
509 pattern because they are not already fully specified in the smaller scale constituent pat-
510 terns. In general, “Emergent properties are irreducible to the microstructure from which
511 they emerge” El-Hani and Emmeche (2000), citing Blitz (1992, p.175) and Kim (1996,
512 p.227-229). That is, if the properties of a system do not supervene on the properties of
513 its components, then it has an emergent property. Accordingly, strong supervenience is
514 usually taken as a definitive negation of emergence, following Kim’s (1984) definition of
515 strong supervenience (also quoted by El-Hani and Emmeche (2000)):

516 “(SS) [A set of properties] A strongly supervenes on [a set of properties] B just in
517 case, necessarily, for each x and each property F in A , if x has F , then there is a property
518 G in B such that x has G and, necessarily, if any y has G , it has F .”

519 Put more simply, “ A -properties supervene on B -properties if and only if a difference
520 in A -properties *requires* a difference in B -properties” (McLaughlin and Bennett, 2021).
521 Hence, if a property of a biological system does not depend *solely* on the properties of its
522 molecular parts, then it is an emergent property and we would have to conclude that the
523 biological system was irreducible in respect to that property. This seeming violation of
524 the reductionist paradigm can arise because properties at one level are the consequence
525 of properties of its lower level components *together with* the arrangement of those com-
526 ponents (the higher level embodied information). Properties and arrangements, being
527 ontologically different entities, cannot be reduced together to a single description at the
528 lowest level. This is not in conflict with the total forcefield-pattern concept of Section 2.2
529 because this irreducibility refers to emergent phenomena, not the patterns (these points
530 are elaborated in the Appendix and a more comprehensive analysis of the separation of
531 property emergence from system emergence is provided in Ellis (2020)).

532 Returning to the case of ATP synthase, the highest-level pattern translates the flow
533 of protons across a membrane into rotation of a large molecular complex and it is this ro-
534 tation, not the pattern, that is the emergent phenomenon (see Fig. 6 with accompanying
535 explanation). As stated in Section 2.2, a pattern can only contribute to cause (other than
536 self-reinforcement) in relation to another pattern and we see that the ATP synthase is an
537 interconnected set of patterns at multiple levels, interacting with one another through
538 their influence on one another’s force fields, i.e. through efficient causes. In general, we
539 can attribute to any assembly at level L : ${}^L\mathbf{A}$, a set of *potential* efficient causes ${}^L\mathbf{G}$, i.e.
540 those possible effects that the assembly’s force field may have on any other assembly.
541 Whenever ${}^L\mathbf{A}$ interacts with any other ${}^M\mathbf{B}$ of level M , the set of efficient causes that
542 can actually occur is selected from the mutual interaction of forcefield patterns (since
543 efficient cause is a relational phenomenon). However, there is in this no restriction that
544 M must be equal to L . If it is equal, we would call the interaction between the two
545 assemblies ‘same-level’ causation; if $M > L$, we would say ‘upward causation’ and if
546 $M < L$, it would be ‘downward causation’.

547 3.2 Downward causation

548 The idea of downward causation remains controversial as several philosophers of science
549 continue to reject it (especially following Kim (1998)). Notably, Craver and Bechtel

550 (2007) argue that “the conception of causation as a physical connection between two
551 things does not accommodate interlevel causes between mechanisms and their compo-
552 nents because mechanisms and their components are distinct events, objects, or pro-
553 cesses.” In the present terminology, Craver and Bechtel (2007) are asking if cause in-
554 volves the transfer of exchange particles (force), then how can this be between a compos-
555 ite (higher level) and one of its constituent parts? The answer is that it is not, instead,
556 the vector sum of forces from all the members of the composite (combined) acts on
557 (transferring exchange particles with) each and every one of the constituent members
558 (recalling the whole-forcefield concept of causation from Section 2.4). But cause is more
559 than these forces, it is also the constraint by pattern information upon them and the
560 pattern, in the case of downward causation, is the form of the composite whole (the
561 macro-level). There is no principle to restrict relationships among patterns formed at
562 different levels because relationships in pattern are just geometry. As we saw in the pre-
563 vious section, a pattern of patterns is in fact a single pattern with a low frequency peak
564 in autocorrelation (mutual information), indicating the higher level order. In material
565 (molecular configurations) it is also a set of spatially localised minima in free energy
566 (the individual molecules that form the composite whole). Craver and Bechtel (2007)
567 contend that any part of a whole is, by being a part, never able to spatiotemporally
568 intersect with the whole. This is because “if a conserved quantity is possessed by one
569 of the components (say a mass or charge), that conserved quantity is also part of the
570 whole.” My answer is that forcefields of the individual parts (e.g. atoms) are indeed
571 constituents of the whole, but the combined pattern they make as a whole belongs to
572 the whole and not to the parts.

573 What is really happening in downward causation is that the forcefield generated by
574 a part (e.g., constituent molecule) interacts with the pattern of the combined forcefield
575 of the whole (including its own) in a way that produces an energy minimising pattern
576 for the part (within the whole) that differs from that of the part in isolation. This
577 is exactly what happens in the case of the ATP synthase complex where the active
578 site is seen to distort (conformational change) in response to the force applied by the
579 asymmetrically shaped armature protein (γ subunit), which rotates as a consequence
580 of dynamics occurring at the next higher organisational level (Ma et al., 2002) (see
581 MRC Mitochondrial Biology Unit (2020) for instructive animations). The higher level
582 pattern of the rotating γ subunit constrains the directions of inter-atomic forces in the
583 active site of the β subunits, producing the efficient cause of conformation change in
584 these active sites, which in turn alternately grasp and release the small molecules of the
585 ADP/ATP/Pi cycle. It works because the energy minimising spatial configuration of the
586 active site changes with its forcefield context (i.e., as the pattern of the whole changes).
587 In the language of emergence: a change in the properties of the micro level (the active
588 site) is induced by the change in the properties of the macro-level (whole ATP synthase
589 complex), which is emergent from the micro-level of molecular shapes. Heuristically, we
590 might say that at the inter-atomic scale of the active site, functional changes take place
591 that can only be conceived of with knowledge of the higher-scale pattern, which ‘reaches
592 down’ to distort those inter-atomic distances. More deeply, we see that it is the patterns

593 (information) that are ontologically important in determining the causal relation among
594 levels, it is not the forces they constrain. The macro-level of the whole ATP synthase
595 complex embodies macro-level information in its structure (the high level pattern), this
596 information changes as the micro-level proton flow pushes the rotor proteins (dynamic
597 pattern), which in turn apply a force on the stator proteins which change in direction
598 and magnitude as the rotor turns (macro-level dynamic) resulting in a micro-level change
599 of pattern (the distortion of the active site with its effect of alternately binding and
600 releasing ADP/ATP). So here we see downward causation as the effect of a dynamic
601 macro-pattern imposing a change on a constituent micro-pattern, resulting in efficient
602 cause directed from the micro-level (proton flow) to the macro-level (protein complexes)
603 and back down to the micro-level (the active site). The macro-level pattern organises
604 the action of forces from the proton flow to the active site and that is essentially its
605 function. Finally, note that none of this is strictly synchronous action, though at the
606 speed of light over such small distances, it appears so.

607 By regarding efficient cause as the informed constraint of forces, clearly delineating
608 the separate constituents—information and force—we can have a simple mechanism-
609 based understanding of downward causation. It can be illustrated in a very simple and
610 graphic way by soap bubbles on the surface of water: alone they are hemispherical
611 (energy minimising), but when formed together as a group, they adhere and distort
612 into an approximately hexagonal shape, characteristic of space and energy minimising
613 packing. The shape of level L structures is determined by the configuration (embodied
614 information) of level $L + 1$. This is a case of downward causation involving change
615 in the constituent parts of the whole. It is not one of the philosophically trivial kind
616 (Craver and Bechtel, 2007; Kistler, 2009) in which either a) separate systems described at
617 different levels are causally linked (e.g., when a person (one system) pulls a rubber band
618 (the other system), atoms are displaced in the band) or b) causal links are essentially
619 constitutive (e.g., when a wheel turns, its constituent atoms also move). Kistler (2009)
620 recasts downward causation as a process of constraint by $L + 1$ on L in response to the
621 rejection of downward causation by Craver and Bechtel (2007) and that is consistent
622 with the mechanistic concept (presented herein) of $L + 1$ information constraining forces
623 that act in level L . In other words: **downward causation is efficient cause that is**
624 **informed by information embodied at the higher level of pattern.**

625 3.3 Closure to efficient causation

626 The term closure to efficient causation refers to a property of hierarchical cycles, following
627 Rosen (1985), in which the hierarchy refers to the containment of one efficient cause
628 within another. This can be understood using the relational biology language of category
629 theory: for any two mappings (morphisms) $f \in H(A, B)$ and $g \in H(C, H(A, B))$, each
630 representing efficient causes (as in any of Fig 5), we see that g takes elements in the
631 set C of material causes (more precisely, patterns) and maps them to a codomain which
632 is a set of mappings (i.e. another set of efficient causes), specifically the member f
633 which transforms members of A to members of B . Concretely, this is achieved when
634 an efficient cause transforms a pattern in matter into one that then has the ability to

635 effect another efficient cause (i.e. the pattern is reconfigured by the first efficient cause
 636 so that it constrains forces such that another efficient cause results). This is distinctly
 637 different from a mere concatenation of efficient causes, such as $C \xrightarrow{g} A \xrightarrow{f} B$, where
 638 g and f transform a pattern in C into a pattern in B via an intermediate pattern in
 639 A : the point is that A is a set of patterns, not of efficient causes, so $C \xrightarrow{g} A \xrightarrow{f} B$
 640 B is termed ‘sequential’, rather than ‘hierarchical’ (see Louie (2009); Louie and Poli
 641 (2011) for more detail) . Closure refers to the case when the output end of a system
 642 of connected mappings is equivalent to the input end, forming a loop (a cycle). The
 643 loop is a hierarchical cycle only if every efficient cause required for it is contained within
 644 another efficient cause that is part of the loop. This is equivalent to requiring the loop
 645 to have no exogenous efficient causes, which means that for a hierarchical cycle, every
 646 causal part of the cycle is itself caused by the cycle: hence it is a *clef* system. For
 647 example, if $f \in H(A, B)$, $g \in H(C, H(A, B))$ and $k \in H(D, H(C, H(A, B)))$ and also
 648 $B \equiv H(D, H(C, H(A, B)))$, then the system of efficient causes $\{f, g, k\}$ is a *clef* system.
 649 (Louie and Poli, 2011, Section 2.5) point out that “Both the hierarchy of containment
 650 and the cycle are essential attributes of this closure” and also that the “accounting (and
 651 tracking) of *all* efficient causes in an entailment system is crucial in our understanding
 652 of hierarchical cycles, one needs to preserve every [efficient cause]”. In practice, closure
 653 and hierarchy together impose a very strong requirement on a system.

654 Using our example, the ATP synthase complex may supply ATP-energy to a proton
 655 pump crossing the same membrane and this pump may maintain the trans-membrane
 656 proton gradient which drives the ATP synthase complex. One might think that here a
 657 set of patterns produce an efficient cause which results in the transformation of another
 658 set of patterns to produce an efficient cause that transforms the first set of patterns such
 659 that it produces the first efficient cause and so on, in a cycle, but that is not enough
 660 to claim that we have a *clef* system before us. Those familiar with relational biology
 661 might say that this system is a sequential cycle, i.e. closed to material cause. But
 662 if material cause is micro-formal cause and formal cause, without forces, is unable to
 663 achieve change, then that is strictly impossible. In this system, there are forces and
 664 they are constrained by patterns, so we do have efficient causes. But analysis shows
 665 that not all the efficient causes involved are contained hierarchically by efficient causes
 666 within the cycle (Fig. 6), since efficient causes such as R_H and F_γ stand out as ‘bristles’
 667 of exogenous origin around the cycle.

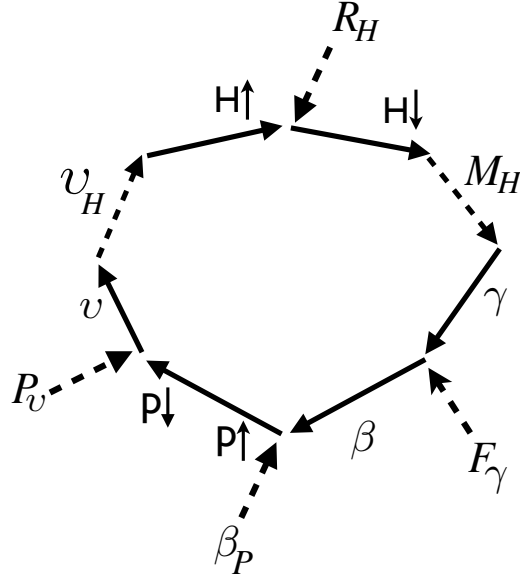


Figure 6: Causal analysis of the ATP synthase / proton pump system showing efficient causes (dashed arrows) are both part of the cycle and exogenous to it, so the system is not closed to efficient causation. Starting with protons (H) in the high energy state (H \uparrow) (concentrated e.g. in the inter-membrane space of a mitochondrion), they then relax (material cause denoted by the solid arrow) under electrostatic and kinetic forces, but are constrained to flow through the proton channel in the ATP synthase, by its pattern (efficient cause R_H). Since this pattern was not caused by any part of the cycle, it is exogenous. The constrained flow creates the proton motive force that is efficient cause M_H for rotating the γ -subunit (the symbol γ represents this rotation which is a change in formal pattern, hence a material cause). That rotation changes the direction of the force applied by the γ -subunit to the β -subunit, but the force itself is produced and constrained by the *pre-existing* pattern of atoms in the γ -subunit, which all move together as one. Because its formal cause is pre-existing, the efficient cause (F_γ) of the γ -subunit force is exogenous to the cycle. F_γ causes a conformation change (material cause) to the pre-existing pattern of the β -subunit, to which phosphorylation is coupled, represented by β_P , resulting in ATP (P \uparrow). Hydrolysis-coupled conformation change in the proton pump v returns ATP to ADP+P_i (P \downarrow) only because of the pre-existing pattern of the proton pump, hence the material cause v depends on exogenous efficient cause P_v . However, like the proton motive force M_H , the proton pump exerts efficient cause v_H - constraining forces - upon the protons, driving them back into the H \uparrow state.

668 These exogenous efficient causes represent the necessary effect of pre-existing pat-
669 terns, without which the system would not function. In the system, pre-existing pat-
670 terns are varied by constrained forces with causal effect: conformation changes in the
671 β -subunit and proton pump; rotation in the γ -subunit and translation for the protons.
672 But pre-existing patterns are not created by efficient causes belonging to the system.
673 Each variation of pattern in the loop can be considered as a material transformation
674 (change of form) and because material transformations have a physical cause, forces
675 must be engaged (and appropriately constrained), so underlying the material transfor-
676 mations, we must find efficient causes. Despite the material transformations composing
677 a loop, constituting closure to material cause by underlying micro-efficient causes, the
678 loop is not a *clef*-system because additional exogenous efficient causes are also necessary.
679 Enclosure of efficient causation definitively entails all the necessary efficient causes in
680 the loop, they must all be endogenous and we do not see that here.

681 Significantly no example of a *clef*-system can be provided at this molecular level
682 of detail yet: the minimal known case of a *clef*-system is that of the whole living cell
683 for which the model provided in Hofmeyr (2021) is the most detailed current causal
684 examination. That is because requiring all efficient causes to be endogenous restricts
685 *clef* to mean that all the components of the system cause one another to be: the efficient
686 causes amount to the fabrication and assembly of the parts that are in turn responsible
687 for the causes. Here, *clef* is not a claim that molecules make themselves, but rather
688 that the system composed of them makes copies whilst retaining the organisation of
689 them, materially different molecules replace their predecessors in order to maintain the
690 organisational integrity: the embodied information is maintained by diachronic, not
691 synchronic causation. Indeed, most of the functionally crucial molecules are fabricated
692 and assembled by the function of the whole system that includes a previous generation
693 of them. But one more ingredient is needed to achieve this, as we shall see next using a
694 more general description.

695 Describing a cell as closed to efficient causation was shown in Hofmeyr (2018) to
696 be consistent with Von Neumann’s constructor theory of self-reproduction (Von Neu-
697 mann and Burks, 1966), which represents reproduction as $(P + Q + R) + \phi(X)$ where
698 P is a ‘fabricator’, $\phi(X)$ is the ‘blueprint’ (information content) of machine X , Q is a
699 ‘blueprint copier’ and R a controller. Hence, there needs to be a reproduction machine
700 plus information about what to reproduce and both have to be duplicated for self re-
701 production. Cellular life conforms to this arrangement by encoding $I = \phi(P + Q + R)$
702 in the form of DNA which acts as formal cause, leaving the information embodied by
703 $P + Q + R$ to inform efficient cause. The distinction between digital (algorithmic) and
704 analogue information referred to by Walker and Davies (2013) and Walker (2017) is
705 this same distinction between information embodied for purely formal cause and for
706 efficient cause. Hofmeyr (2021) resolves construction into two distinct parts: *fabrica-*
707 *tion* being the building of biomolecules, particularly polypeptides and polynucleotides,
708 and *assembly* (following it) being the folding of polypeptides into functional forms and
709 the organisation of these into a functional spatial pattern. With the representation of
710 ontological causal structure (Fig. 4 b), a model of the cell was constructed that explic-

711 itly includes formal and efficient causes combined into a *clef* system, with $I = \phi(X)$
712 explicitly identified with DNA and P, Q, R matching known biochemical subsystems:
713 Hofmeyr’s (2021) fabrication-assembly (F, A) model. Expanding (Fig. 4 b) to identify
714 all the main metabolic, anabolic and informational flows Hofmeyr (2021) shows that
715 the cell must use an independently embodied source of information to achieve closure
716 to efficient causation, making it an *informed system* (defined in the Introduction). The
717 causal role of this information is purely formal, it does not exert efficient cause in and of
718 itself, instead it has to be re-embodied into forms that do exert efficient cause and this
719 transfer of information from one embodiment to another is the process of transcription
720 and translation, which necessarily entails biological coding (Barbieri, 2015). Specifically,
721 since $I = \phi(P + Q + R)$ is formal cause, it needs to be (literally) transformed to become a
722 source of efficient cause and that is accounted for in the (F, A) model of Hofmeyr (2021)
723 by explicitly including the causal role of ribosomes and their related molecules.

724 But why is this additional information necessary at all? To inform the efficient cause,
725 information in $P + Q + R$ must be embodied so as to constrain the forces that result in
726 fabrication, copying and control. But to act as $I = \phi(P + Q + R)$, it needs to be in a form
727 that produces no appreciable efficient cause (just like the tape of the Jacquard loom). It is
728 not possible for the same pattern to act in both ways simultaneously. Logically, it seems
729 self-evident that a thing cannot be both the basis for efficient cause and constrained not
730 to produce efficient cause at the same time and place. In other words the formal (nucleic
731 acid-based) $I = \phi(P + Q + R)$ is kept from exerting direct efficient cause by encrypting it
732 and this encryption simultaneously protects it from (all but very select) efficient causes
733 in $P + Q + R$. The separation of roles for this information is universal across life and Von
734 Neumann himself may have seen the necessity for it (based on his theory of complicated
735 automata). In Burk’s account of the 1948 Illinois lectures (Von Neumann and Burks,
736 1966) there is a hint of this “... it is preferable to proceed, not from original to copy, but
737 from verbal description to copy” (p.84). That ‘preference’ is increased by the way Von
738 Neumann’s replicator works, the copying machine Q has to make two copies of $\phi(X)$
739 (p.85). Significantly, Von Neumann refers to $\phi(X)$ as a ‘memory’ and in his cellular
740 implementation (a forerunner of Conway’s Game of Life), he requires a particular cellular
741 automaton to be ‘embedded’ as an initial condition (p. 108), effectively constituting the
742 memory and reflecting the historical contingency that characterises life. Burk comments
743 on the (sadly incomplete) work: the ‘strongest’ solution for the self-reproduction problem
744 required “a complete description of the secondary [daughter system], expressed by the
745 linear array of cells \mathbf{L} , to be attached to the primary [parent]” (p. 118). I am unaware
746 of a proof of this, but perhaps demonstrating that a replicator is an *inference device*, as
747 defined by Wolpert (2008) would provide one. More practically, the search for a ribozyme
748 capable of self-replication (Tjhung et al., 2020; Khatib and Raslan, 2021) demonstrates
749 the difficulty of simultaneously using information to effect self-construction and to be
750 the blueprint for that process. A whole ribosome is far simpler than an organism and
751 Hofmeyr (2021) correctly points out that even the ribosome cannot self-replicate. Even
752 if that were possible, it would leave no room for error correction, which has been a major
753 stumbling block to the creation of synthetic ribozymes.

754 Obviously nucleic acids embody additional information, but they are not the sole
755 source of information to the cell. Another insight of Hofmeyr (2021) was recognition
756 of the intracellular milieu as a functional component of the *clef* system, responsible
757 for e.g., protein folding. This milieu has to be maintained within tight biochemical
758 parameters, for which a closed-loop control network of transducers and actuators (e.g.,
759 ion pumps) is necessary. A share of both the milieu (cytosol) and the membrane, with
760 all its transmembrane components embedded, is physically transferred to the daughter
761 cells. All closed-loop control systems need set-points which are internally embodied
762 information (formal cause) representing the *goal*—a special point in an objective function
763 (e.g., osmotic potential). Set-points for homeostasis are ubiquitous among the networks
764 of cellular biochemical pathways, but we still do not know how, in general, they are
765 embodied or encoded (Reed et al., 2017). It is likely that they are, at least in part,
766 transferred along with the material components of cytosol and membrane. Set-points are
767 another example of information embodied to function as pure (stand-alone) formal cause
768 and seem to be unique to life (Farnsworth, 2017).

769 3.4 Ultimate cause, goals and functions

770 The set-point represents a goal in an objective function (e.g., osmotic potential) and
771 with that a *purpose* for control is established. Homeostasis is apparently unique to life
772 and certainly implies an intention or goal. Once we have a goal-seeking purpose, we
773 can define *function* as working to achieve that goal. Functional information is that
774 which contributes to the functioning of the whole and in the case of organisms, that
775 corresponds with the *master function* (Auletta et al., 2008) of the organism, which is
776 established by evolution as maximising life-time reproduction success (biological fitness)
777 (Farnsworth, 2017). Function does not imply teleology if defined as a *process* enacted
778 by a system **A** at emergent level L which influences one or more processes of a system
779 **B** at level $L + 1$, of which **A** is a component part (Farnsworth et al., 2017). But once we
780 identify a master function for the whole system, teleology is unavoidable (Mossio and
781 Bich, 2017). Homeostasis is necessary because the functioning of the whole requires the
782 living system to be within a particular range (sub-set) of states, though its environment
783 may change. It also implies a means of detecting the changing environment, without
784 being determined by it in a linear chain of efficient causation (as would be the case
785 for a non-*clef* system). This requires isolation from exogenous causation, but not from
786 the information embodied by exogenous forces. The stripping of force from exogenous
787 efficient causes, leaving only the formal causes (information) is achieved by the plasma
788 membrane of the cell plus its many embedded transducers (Farnsworth, 2018). Again we
789 see the incorporation (literally) of patterns that separate the formal information from
790 the force, resolving efficient cause into its fundamental components.

791 3.4.1 Transduction and causal isolation

792 The action of a transducer, which detects patterns of forces on one side of a barrier and
793 relates them as information in signals on the other side is approximately performing this

794 stripping of formal cause from efficient cause that was described in terms of a Jacquard
795 loom in Section 2.4.4. In first messenger–second messenger signalling, transmembrane
796 molecules can change the way information is embodied and in so doing totally change
797 the nature, arrangement and magnitude of the forces that accompany its embodiment.
798 For example when a retinal molecule absorbs a single photon, it extends to its *trans*
799 conformation from the flexed *cis* conformation, producing a distortion in the shape
800 of the much larger opsin protein (a G-protein coupled receptor) that holds it. This
801 conformational strain triggers a second messenger signal via a complicated cascade, part
802 of which sees an active site in the rhodopsin molecule bind to a G-protein and by doing so,
803 activates it. The internal chemical signal, not a photon, is available for amplification via
804 a chemical chain reaction, and in the case of the retinal photo-isomerisation, the signal
805 eventually triggers the release of neurotransmitters from where a nervous system can
806 amplify by mutual excitation of neurones; clearly the photon itself has been replaced with
807 a signal representing the arrival of a photon. Even more clearly, when physical pressure
808 is applied to a cell, especially one adapted to detect physical forces, mechanosensory
809 systems embedded in the membrane, based on gated ion channels, transform the physical
810 force into a chemical signal (Gillespie and Walker, 2001). The information (e.g., vibration
811 frequency) is retained by the transducer, but its efficient cause is stripped of its force
812 by the transducer/membrane complex, leaving a signal, again embodied in signalling
813 molecules, or ionic concentrations. Once this happens, there is no longer an inevitable
814 causal link between the external agent (physical force) and internal response, instead a
815 causal branching point has been created Ellis and Kopel (2019). Branching points are
816 forks in causal relations under the control of an additional efficient cause, which switches
817 from one causal branch to the other (in effect both efficient causes are necessary to
818 determine the effect). For example ion channels may open upon reaching a threshold of
819 strain in the membrane and this threshold may be determined by internal control using
820 a set-point, so that the effect of the strain could become functional at the whole system
821 level.

822 **3.4.2 All together - the living cell**

823 Now we can see a living cell as a *clef* system which also embodies the information
824 needed to inform its self-construction (both fabrication and assembly), and homeostatic
825 control, following the causal architecture described in Hofmeyr (2021). It is a large set
826 of efficient causes acting across levels; a dynamic pattern in a very complicated (mainly
827 electrostatic) forcefield. It is not only *clef*, but by using its physical boundary with
828 embedded transducers, along with embodied control information (set-points), it also
829 achieves cybernetic autonomy (transforming from cause-effect to signal-response) via a
830 nested hierarchy of homeostatic systems. This hierarchy of signal-response systems phys-
831 ically forms the basis of decision making that leads from the most basic homeostasis up
832 to action valuation systems (Farnsworth, 2017, 2018). The very idea of decision making
833 implies autonomy, options and criteria to measure them by (Noble and Noble, 2018).
834 Embodied information serving as set points provides the criteria as goals in physiological
835 objective functions (variables). This embodiment of formal cybernetic information is a

836 prerequisite for ultimate cause (Farnsworth, 2017), that most controversial of Aristotle's
837 four, which seems unique to life (Mossio and Bich, 2017). It pre-supposes *purpose*
838 which is necessarily subjective and cannot be defined without reference to an agency
839 to which it belongs. This, with its teleological implications, may be permitted only in
840 the case of organisms because they alone among natural systems have the properties of
841 causal agents (Bich and Damiano, 2012; Friston, 2013; Froese et al., 2007; Kauffman and
842 Clayton, 2006; Varela, 1979). Two attributes are necessary and apparently sufficient for
843 this causal agency: first that systems be *clef* and second that they possess autonomous
844 information that formally acts as at least one set-point for homeostasis. Living cells
845 include hundreds of set-point based homeostatic systems which interact with the formal
846 information of the genome, these together constituting a computer that runs the cellular
847 operating system Auletta et al. (2008), enabling the cell to respond to its environment
848 and execute fitness enhancing actions.

849 4 Discussion

850 The ideas presented here can be summarised as follows. Form is the arrangement of
851 particles in space and time. Associated with every particle is a forcefield of character-
852 istic shape and whenever two or more particles are sufficiently close to significantly
853 interact, it is because their forcefields sum over space to produce a new combined shape.
854 If this shape persists in time, it is because the configuration of the particles (pattern) is
855 thermodynamically favourable compared to alternatives ($\Delta G < 0$) and the pattern then
856 embodies information. The pattern, in turn, constrains the vectors of forces among the
857 particles (by making specific the direction and magnitude of exchange particle transfers
858 among them). Formal cause is this constraint of forces by pattern (information). Eff-
859 icient cause is the physical effect of formal cause and the alternative of unconstrained
860 physical force (absence of formal cause) manifests as heat. Material cause is atomic-
861 level efficient cause. Multiple levels of organisation arise from the spatial distribution of
862 mutual information (spatial autocorrelation) in the overall pattern. It is the patterns,
863 not the forces they constrain, that determines the causal relation among organisational
864 levels. As a consequence, there is no impediment to inter-level causation. Emergent
865 phenomena arise when a higher level pattern informs efficient cause. An important ex-
866 ample of that is the emergence of downward causation, whereby small scale patterns are
867 varied by the larger scale (e.g. the rotating armature protein inducing conformational
868 change in the active site of the β -subunit of ATP synthase). Circular efficient causation
869 (*clef*) is diachronic not synchronic and involves a special case of downward causation
870 in which higher level patterns organise lower level patterns to result in the fabrication
871 and assembly of copies of themselves. Systems possessing this property must also be
872 informed systems, meaning they must incorporate an additional source of formal cause
873 over and above that which informs their efficient causes (i.e., they need a memory).
874 Above all, these properties make the living cell uniquely potent as a physical system.
875 Finally, ultimate cause can only apply to a *clef* system and requires autonomous formal
876 cause (at least one set-point) to establish a goal, from which purpose and function can

877 be defined and without which ultimate cause makes no sense.

878 Throughout this informationist account, the concept of organisation by constraints
879 within living systems is crucial. It was developed by Juarrero (1999) in response to
880 a perceived inadequacy of conventional theory to account for emergence. She distin-
881 guished between context-free (effectively external) constraints and context-dependent
882 (self-organising) constraints which act as a form of downward causation; significantly
883 calling the action of an object “informationally dependent and constrained behaviour”
884 (Juarrero, 2000, p.30). Context-dependent constraints were later differentiated into first
885 and second order, the former enabling emergence from joint probabilities (correlation)
886 among interacting parts; the latter implicating the symmetry breaking that leads to
887 reinforcement of pattern, non-linearity and dependence upon the history of the system
888 (Juarrero, 2009). This was inspired by the probability theory approach towards e.g.
889 complex ecological systems, especially exemplified by Ulanowicz (2019). We see here the
890 beginnings of a coherent theory recognising the mutual dependence of state-space proba-
891 bilities among system components and the connection of that (not yet equivalence) with
892 information. Montévil and Mossio (2015) reiterate the idea of self-control by constraints
893 in an effort to specify efficient cause in biological systems, taking their inspiration from
894 the ‘work-constraint cycle’ concept of Kauffman (2000). For Montévil and Mossio (2015),
895 constraint closely matches the idea of efficient cause developed by Rosen (1973, 1985).
896 This was resolved into formal and efficient causes, for which information has an explicit
897 role in the fabrication-assembly model of the cell developed by Hofmeyr (2021). The
898 work presented here strengthens that by explicitly identifying information as the partic-
899 ular constraint on physical force that acts as the basis for all causation and by showing
900 how information embodied in lower-level patterns (e.g. molecules) is manipulated by
901 higher level patterns in organisms to effect autonomous agency. This emphasises that
902 life is quintessentially an emergent phenomenon - strictly not accessible from the study
903 of component parts alone.

904 The reductionist approach has been so successful that it has misguided us towards
905 believing that the small scale is the only real one and that all processes are in fact
906 processes at that scale. Understanding that everything, except elementary subatomic
907 particles, exists because of information embodied in the particular arrangement of those
908 particles, enables us to see it the other way round. Certainly, all causes can be traced
909 back to the constraint of physical forces acting among all the particles present, these
910 constraints being the geometric configuration of the particles in space and time. But
911 realising this can give us a radically integrative view telling us that material objects
912 composed in a hierarchy of levels of organisation and interacting with one another via
913 physical forces are in fact all parts of one pattern of elementary particles with symmetry
914 breaking occurring at multiple spatial scales, from which we identify the levels. For
915 each fundamental force, the pattern creates a single forcefield: the vector sum of forces
916 emanating from all the particles and influencing the movement and position of them
917 all. Rather than the smallest level being the fundamental basis of reality, it seems the
918 largest level, the one where the forcefield is a unitary whole with a particular (and typ-
919 ically changing) pattern, is the source of the reality that we experience. In this context,

920 organisms are special because, as patterns within the whole, they possess both closed
 921 loops of efficient causation (albeit diachronic) and also the information, embodied as
 922 part of their pattern, that informs the fabrication of the patterns from which they are
 923 composed and by which they are self-regulated. The form of an organism is necessarily
 924 (but selectively) closed by a material boundary (one or more cell membranes) and neces-
 925 sarily contains a template-memory that has accumulated, presumably through evolution
 926 (we do not yet know how) and arranged so that it creates copies of its own pattern, lead-
 927 ing both to self-maintenance and also to self-replication. Organisms are self-informed
 928 dynamic patterns within the whole (a considerable advance on e.g. vortices), having the
 929 properties of autonomy derived from their internalised information that gives them a
 930 goal and the autonomy to pursue it, but they are ultimately a part of the whole. In this
 931 way, life is not separate from the universe, instead, it is the greatest known elaboration
 932 of the information structure of the universe.

933 The concepts proposed here are far from the full answer to overcoming the challenge
 934 of biology to physics, but the resolution of efficient cause into force and formal cause
 935 (information), with all its consequences, seems to provide a sufficiently fresh perspective
 936 to stimulate further progress. There are several unanswered questions, notably it remains
 937 a mystery how the information needed for autonomous operation of a living cell was
 938 accumulated in the first place. More detailed problems such as the mechanisms of protein
 939 folding and the way the protein parts of molecular machines are correctly assembled and
 940 the whole inventory of parts is managed by the cell, remain to be answered by further
 941 research.

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948 Appendix - the irreducibility of hierarchies of biological 949 function

950 The following is a simple analysis of emergence using the concepts introduced in Sec-
 951 tion 2.2 of the paper.

952 For any level L in an organisational hierarchy of pattern, let ${}^L\mathbf{A}$ be an assembly of
 953 n_L components (lower-level assemblies) $\{{}^{L-1}\mathbf{A}_1 \dots {}^{L-1}\mathbf{A}_{n_L}\}$, configured in space as a
 954 pattern of patterns ${}^L\mathbf{C} = \{{}^{L-1}\mathbf{C}_1 \dots {}^{L-1}\mathbf{C}_{n_L}\}$. For the first level assemblies, we have
 955 ${}^1\mathbf{A} = \{e_1 \dots e_n\}$, where e_i are fundamental particles, each with an associated force-field
 956 f_i and these are configured in space by ${}^1\mathbf{C} = \{\mathbf{z}_1 \dots \mathbf{z}_n\}$, where each \mathbf{z}_i is the set of
 957 relative coordinates of particle e_i (for relative, take any one particle as the origin and

958 measure coordinates from there). Every pattern constrains forces in the sense stated in
959 Section 2.4, irrespective of its level: every ${}^1\mathbf{C}$ constrains the forces emanating from the
960 particles it places in space and any higher e.g. ${}^2\mathbf{C}$ adds further constraints by virtue of
961 specifying the relative position of each member ${}^1\mathbf{A}$ within ${}^2\mathbf{A}$, following the principle
962 set out in Section 2.4. For example if ${}^1\mathbf{A}$ was a water molecule and ${}^2\mathbf{A}$ an ice crystal,
963 the arrangement of molecules in ice would be ${}^2\mathbf{C}$).

964 For strong emergence (Chalmers, 2006), it is necessary to show that the properties of
965 ${}^L\mathbf{A}$ do not supervene on the properties of its member parts ${}^{L-1}\mathbf{A} = \{{}^{L-1}\mathbf{A}_1 \dots {}^{L-1}\mathbf{A}_{n_L}\}$,
966 thus implying that a change in properties of ${}^L\mathbf{A}$ can be brought about without changing
967 any of those of its component parts ${}^{L-1}\mathbf{A}$. Clearly, the level- L pattern ${}^L\mathbf{C}$ can change
968 without changing any of its component parts $\{{}^{L-1}\mathbf{C}_1 \dots {}^{L-1}\mathbf{C}_{n_L}\}$, simply by rearrang-
969 ing those parts, noting that ${}^L\mathbf{C}$ specifies a *particular* arrangement of the ${}^{L-1}\mathbf{C}$ patterns.
970 But we still need to establish whether a change in level- L pattern alone can result in a
971 change in level- L properties.

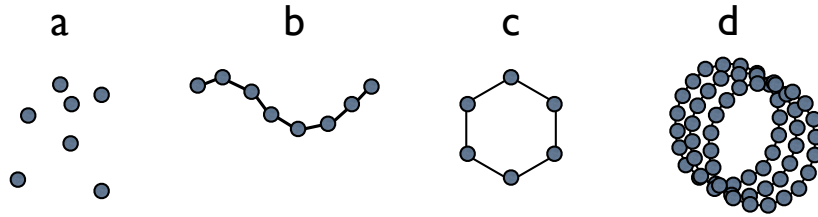


Figure 7: Emergent properties of levels of pattern: level-1 elementary particles (a) have only their own properties, e.g. charge and spin. A level-2 pattern such as a string (b) has new properties, e.g. length. A level-3 pattern made with the string, e.g. a ring (c) can have a diameter and shape (hexagonal in this case). A string can also be coiled to make a tube, as in the tobacco mosaic virus (d): the coiling is a level-3 pattern and has new properties such as diameter and flexibility. If it were to be pinched to form a figure of eight cross-section, it could branch and from this a ramiform level-4 pattern could be built, making e.g. an arterial tree.

972 Let us associate with every ${}^L\mathbf{C}$, a set of properties, ${}^L\mathbf{P}$, for example geometric prop-
 973 erties such as those of a string of particles (Fig. 7.b) and those of the string formed into a
 974 ring (Fig. 7.c), or a cylinder formed from a spiral of the string (as in the tobacco mosaic
 975 virus, Fig. 7.d). Note that in forming a string, we change the spatial dimensionality of
 976 the assembly and further change it when forming the ring and spiral. These are examples
 977 of symmetry breaking, whereby the pattern no longer appears the same when viewed
 978 from any angle. Symmetry breaking was strongly identified with emergence by Anderson
 979 (1972) and has since been an important part of its explanation in physics (e.g. Ellis,
 980 2020). The precise meaning of ‘properties’ remains somewhat obscure, so let us assume
 981 that (other than for fundamental particles) properties are what we recognise in higher
 982 level patterns as enabling efficient causes that could not be attributed solely to the lower

983 level patterns (this is consistent with the definition in Baas and Emmeche (1997), used
 984 by El-Hani and Emmeche (2000), though they did not explicitly refer to efficient causes).
 985 For example, the strength of a material depends on how its atoms are arranged (level-1
 986 pattern) and a tube formed from a spiral enables the containment and direction of fluid
 987 flow; these potentialities arising from ‘tube-properties’ (Fig. 7.d), which are what we
 988 recognise of the level-2 pattern. That is, properties of level- L are *observed*, recognised
 989 and ascribed; they exist specifically because of the level- L pattern, hence they depend
 990 on information embodied by the level- L pattern and in fact, according to El-Hani and
 991 Emmeche (2000), they arise from the constraining of the relations among the parts, in
 992 space-time, such that “the pattern of constraints realizes and thus, explains ${}^L\mathbf{P}$ ” (they
 993 used a plain P notation). Given this, we can identify the properties of the particles
 994 making up a string as ${}^1\mathbf{P}_1$, those of the string itself as ${}^2\mathbf{P}_1$ and those of the ring as
 995 ${}^3\mathbf{P}_1$ and the spiral cylinder as ${}^3\mathbf{P}_2$ to compose a hierarchy of patterns, with particles at
 996 level-1, the string at level-2 and the ring and cylinder each at level-3.

997 Since the above definition of a property entails efficient causes, we also need to
 998 associate a repertoire of *potential* efficient causes, ${}^L\mathbf{G}$ with its pattern ${}^L\mathbf{C}$, which is
 999 no problem since by constraining forces, the pattern can produce these, according to
 1000 Section 2.4 (note there is no necessary relation between the number of components in
 1001 ${}^L\mathbf{C}$, the number of properties in ${}^L\mathbf{P}$ or the number of potential efficient causes in ${}^L\mathbf{G}$).

1002 The constrained forces depend on all the particles in the level- L assembly ${}^L\mathbf{A}$ and
 1003 the level-1 ways they are configured ${}^1\mathbf{C} = \{{}^1\mathbf{C}_1 \dots {}^1\mathbf{C}_{n_1}\}$ and the level-2 ways ${}^2\mathbf{C} =$
 1004 $\{{}^2\mathbf{C} \dots {}^2\mathbf{C}_{n_2}\}$, and so on up to ${}^L\mathbf{C}$ (which has only one member). Other than the
 1005 particles (and their forcefields), that means ${}^L\mathbf{G}$ depends on the patterns at all the
 1006 levels and we can summarise that (without repetition of patterns that are the same) by
 1007 $\{{}^1\mathbf{C} \cup {}^2\mathbf{C} \dots \cup {}^L\mathbf{C}\}$. This, though, is just a decomposition of the total pattern and
 1008 is no more than an information-efficient (compressed) way to describe it, equivalent to
 1009 a description entirely at the first level of fundamental particles.

1010 If that was all ${}^L\mathbf{P}$ depended on, then it could be completely described in terms of the
 1011 total pattern that specifies the coordinates of every fundamental particle. This descrip-
 1012 tion necessarily includes information about the larger scale patterns, but to show strong
 1013 emergence, we would need to identify a block on reducing all the necessary conditions for
 1014 ${}^L\mathbf{P}$ to the lowest level. This block arises from the definition of properties as depending
 1015 on both lower level causes and same-level pattern - two ontologically different things
 1016 existing at two different levels of organisation.

1017 Specifically, the properties ${}^L\mathbf{P}$ of ${}^L\mathbf{A}$ depend on both the properties ${}^{L-1}\mathbf{P}$ of the
 1018 assemblies within ${}^L\mathbf{A}$ and also on the way they are configured by the pattern ${}^L\mathbf{C}$. For
 1019 example, the properties of a ring (${}^3\mathbf{P}$) depend on those of the string from which it
 1020 is assembled (e.g. its length) and *also* the geometric shape of the ring (circular or
 1021 hexagonal, etc.), which are specified by the ring’s pattern (${}^3\mathbf{C}$) and do not exist (even
 1022 as concepts) at the lower levels, even though the possibilities for ${}^3\mathbf{C}$ are brought into
 1023 existence by the string (which is a level-2 assembly: ${}^2\mathbf{A}$). The properties of each of the
 1024 ${}^{L-1}\mathbf{A}$ in turn depend on ${}^{L-2}\mathbf{A}$ composing ${}^{L-1}\mathbf{A}$, all the way down to ${}^1\mathbf{A}$. To illustrate:
 1025 the ring might be a string joined in a tight circle composed of six molecules of type

1026 A and B, (strung together as A-B-A-B-A-B which is the pattern ${}^2\mathbf{C}$). Suppose each
1027 of A and B has the property 1P_A and 1P_B , respectively, of a particular surface charge
1028 distribution (one for A and one for B), determined by the properties of the atoms from
1029 which it is composed and the way they are arranged in the molecules: $\{{}^1\mathbf{C}_A, {}^1\mathbf{C}_B\}$.
1030 By this alternating charge, (a ${}^2\mathbf{P}$ property of the string) the ring acquires the property
1031 ${}^3\mathbf{P}$ needed for it to produce the efficient cause of a molecular motor in the context of a
1032 yet higher level (4) of pattern in atoms. It obtained this level-3 property from level-2
1033 properties in conjunction with its ${}^3\mathbf{C}$. The level-2 properties were obtained, in turn,
1034 from level 1 properties in conjunction with the level-2 pattern of alternating molecules.

1035 Thus, it is clear that properties arise from a conjunction of ontologically different
1036 entities: lower level properties together with patterns. This means that they are not re-
1037 ducible to a single low-level description (as the hierarchy of patterns $\{{}^1\mathbf{C} \cup {}^2\mathbf{C} \dots \cup {}^L\mathbf{C}\}$
1038 was). For this reason, we can conclude that strong emergence is a natural (physical)
1039 consequence of organisational levels having properties that depend on the information
1040 embodied at their (same) level, as well as the properties of their component parts. In
1041 plain language: **because properties at one level are the consequence of prop-**
1042 **erties of its lower level components *together with* the arrangement of those**
1043 **components, they cannot be reduced to a single lowest-level description.** The
1044 properties uniquely associated with each level give rise to the ‘new concepts’ referred to
1045 in some other accounts of emergence and the irreducibility of levels results from hav-
1046 ing to combine ontologically different things to form each of them. This also explains
1047 why property emergence is always associated with causality, rather than mere patterns,
1048 though of course it depends on assuming that properties themselves are more than mere
1049 patterns. Indeed, many refer to them as emergent phenomena.

1050 The analysis just given exposes the problem of subjectivity (dependence on an ob-
1051 server) that lies at the heart of current attempts to account for property emergence (see
1052 e.g. Blundell (2017)). Essentially the problem is that properties cannot be rigorously
1053 defined without including the view-point of an observer because they are the result of
1054 observation. We are left unsatisfied because, as scientists we want there to be a nat-
1055 ural objective meaning for emergence before we are willing to fully accept the idea of
1056 it into main-stream science, which is an objective account of natural systems. What
1057 happens if we let go of properties and instead focus on only those things that are cer-
1058 tainly objective? We may see that what is important about the component assemblies
1059 $\{{}^{L-1}\mathbf{A}_1 \dots {}^{L-1}\mathbf{A}_{n_L}\}$ of ${}^L\mathbf{A}$ in the formation of efficient cause is their repertoire of effi-
1060 cient causes $\{{}^{L-1}\mathbf{G}_1 \dots {}^{L-1}\mathbf{G}_{n_L}\}$. These can be organised into one or more higher level
1061 efficient cause by the level- L pattern ${}^L\mathbf{C}$. It does not matter exactly what the ${}^{L-1}\mathbf{A}_i$ are,
1062 it is their potential effects that matter; in principle, different assemblies may enact the
1063 set of efficient causes, so they are multiply realisable and we may more precisely refer to
1064 equivalence classes of ${}^{L-1}\mathbf{G}_i$. If more than one level- $(L-1)$ assembly can produce the
1065 same ${}^{L-1}\mathbf{G}_i$, then more than one ${}^{L-1}\mathbf{C}_i$ can be responsible for its production, that is, at
1066 least in principle, there is a set $\{{}^{L-1}\mathbf{C}_{i,1} \dots {}^{L-1}\mathbf{C}_{i,J}\}$ which, constraining their particle
1067 forcefields, results in ${}^{L-1}\mathbf{G}_i$. This leaves us in the same position of needing to combine
1068 ontologically different objects at each level to form the efficient causes: this time it is

1069 functional equivalence classes combined with patterns. The effect is the same: we cannot
1070 reduce the combination to a lowest level description.

1071 Satisfyingly, this prohibition on decomposition becomes stronger when the system is
1072 a biological one, for which the relevant efficient causes (of all potential efficient causes
1073 in ${}^L\mathbf{G}$) are those which confer biological function. In this case, every level- L func-
1074 tion ${}^L\mathbf{F}$, is the result of ${}^L\mathbf{C}$ organising components that have biological function sets
1075 $\{{}^{L-1}\mathbf{F}_1 \dots {}^{L-1}\mathbf{F}_{n_L}\}$ (consistent with the Farnsworth et al. (2017) definition of bi-
1076 ological function). These sets are functional equivalence classes (Farnsworth et al.,
1077 2013); certainly an ontologically different entity from the embodied information ${}^L\mathbf{C}$,
1078 so the combination of them with ${}^L\mathbf{C}$ cannot, even in principle, be decomposed into a
1079 level-1 description. The result is the possibility of strong emergence of biological func-
1080 tions. Not only that, but the organising information ${}^L\mathbf{C}$ has the effect of selecting from
1081 $\{{}^{L-1}\mathbf{G}_1 \dots {}^{L-1}\mathbf{G}_{n_L}\}$ those potential efficient causes that are functional in the sense
1082 that they contribute towards ${}^L\mathbf{F}$. Thus in living systems, the nested hierarchy of organ-
1083 isational levels is also a nested set of selection processes, each selecting function from
1084 the potential efficient causes of the assemblies in the level below it. Since the functional
1085 repertoire of each level is a real and essential feature of that level and dependent on this
1086 selection, every level is irreducible.

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